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## research note

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## Proposed Modification to the Charged Hadron Tracking Algorithm in MCNPX

### Summary

Unreasonable results observed in the calculation of a depth/dose curve in water using MCNPX have lead to a reexamination of the logic applied to energy loss and energy straggling while tracking a charged hadron through material. A modified version of subroutine CHG\_PL has been developed and tested which provides a high degree of consistency with LAHET3 calculations.

### I. Introduction

The original problem[1] in which the difficulty was detected was specified as a 157.2 MeV proton beam on water. The protons were tracked through a geometry of planes with 1 mm spacing; energy deposition (F8 tally) was computed in each 1 mm-thick region. To obtain the best possible comparison between LAHET3 and MCNPX, the original input was modified to transport protons with only multiple scattering, slowing down, and energy straggling, and with no nuclear nonelastic or elastic events. The magnitude of the discrepancy is readily discernible in Figure 1.

It is worth noting what *does not* contribute to the problem. First, LAHET3 and MCNPX use the same coding for multiple scattering, applied at steps that are at least comparable. Second, the mean stopping power used by MCNPX within an energy interval of the range tabulation ("energy step") is obtained by integration over the interval; apart from numerics, the method is equivalent to linear interpolation in a range table in LAHET3 application. The pointwise evaluation of the stopping power is the same in both codes.

For purposes of methods testing and validation, proton surface flux tallies at 5 cm, 10 cm and 15 cm depth were also made. The energy distribution of the surface flux is particularly sensitive to application of the energy straggling algorithm. Since the flux on the specified surfaces and the location and shape of the Bragg peak should be independent of any specified intervening geometry, an input with a second geometry was defined, with three regions each 5 cm thick, followed by the same 1 mm-thick regions near the end of range. In the original problem, a proton would be tracked across 150 surfaces to reach a depth of 15 cm, while in the second case it would cross only three.

## II. Tracking Charged Particles in MCNPX

The logic of tracking a charged particle in subroutine CHG\_PL of MCNPX may be described by the following (over)simplified sequence.

1. A charged particle with energy  $E$  is assigned to energy step  $i$ , where  $E_i > E \geq E_{i+1}$ .
2. A random energy straggling increment  $\Delta(E, p)$  is sampled for a step size  $p$  defined by

$$p_i = \frac{E_i - E_{i+1}}{q_i}$$

where  $q_i$  is the mean stopping power in energy interval  $i$ .

3. An effective stopping power  $\tilde{q}_i$  is defined for the current interval by

$$\tilde{q}_i = q_i + \Delta(E, p)/p$$

and the “substep distance” is defined as  $\delta = p/n$  where  $n$  is the number of substeps per energy interval (ESTEP, default =3).

4. A loop is initiated over the  $n$  substeps.
5. The distance to interaction  $d_I$ , distance to time cutoff  $d_t$ , distance to energy cutoff  $d_c$  and distance to surface crossing  $d_s$  are obtained.
6. The tracking distance  $d$  is defined by

$$d = \min(\delta, d_s, d_I, d_t, d_c)$$

and the particle is advanced by  $d$ .

7. The multiple scattering is applied to the directional coordinates for  $E$  and  $d$ .
8. The new energy is defined by  $E - \tilde{q}_i d$ .
9. If  $d < \delta$  or  $E < E_{i+1}$  (and the particle remains to be tracked), the energy interval index  $i$  is incremented and the procedure is reinitiated at step (1) above; otherwise, the substep loop is continued.

Approximations which may cause difficulties are introduced at (3) and at (8) above.

The use of  $\tilde{q}_i$  gives a correct representation of energy straggling *only* when the loop over all  $n$  substeps is exhausted. Surface crossings, interactions, and exiting the energy interval in less than  $n$  complete steps will all introduce some error. Tracking through complex geometry will exaggerate the cumulative error. The method is completely inappropriate for the estimation of energy spreading when passing through a single optically thin region such as a foil.

Adjusting the energy at (8) above introduces an error at every application in which the energy drops out of the current energy interval; in this case, part of the tracking distance  $d$  is actually in an energy range where the stopping power may be greatly different from the  $\tilde{q}_i$  applied. The effect of the approximation is mitigated by many surface crossings, by frequent

scattering events, or by increasing the number of substeps  $n$ . However, at low energies where the stopping power increases with decreasing energy, the energy loss over an extended range will be consistently underestimated; at high energies where the stopping power decreases with decreasing energy, overestimation of energy loss occurs.

### III. The Modified Tracking Algorithm

The modified algorithm for calculating the mean value new energy  $E'$  after a tracking length  $d$  starting from initial energy  $E$  in energy interval  $i$  is given by the sequence of equations:

$$E' = E - q_i d \text{ for } E' > E_{i+1}$$

$$E' = E_{i+1} - q_{i+1} \left( d - \frac{E - E_{i+1}}{q_i} \right) \text{ for } E_{i+1} \geq E' > E_{i+2}$$

and for  $E_{i+m} \geq E' > E_{i+m+1}$  with  $m > 1$ ,

$$d' = d - \frac{E - E_{i+1}}{q_i} - \frac{E_{i+1} - E_{i+2}}{q_{i+1}} - \dots - \frac{E_{i+m-1} - E_{i+m}}{q_{i+m-1}}$$

$$E = E_{i+m} - q_{i+m} d'$$

The energy straggling correction is obtained by applying the sampling for the energy correction whenever the energy is recalculated, using the real tracking length  $d$  and the initial energy  $E$ . Thus, if  $E'$  is obtained as above, the new energy at the end of the step is

$$E'' = E' - \Delta(E, d)$$

The two corrections may be applied separately, as shown in the examples.

### IV. Results

As previously noted, Figure 1 shows comparative results for the calculation as originally presented. Figure 2 provides detail of the location and shape of the energy deposition peak. Note that applying the energy correction alone makes little difference, since the energy is adjusted at the many surface crossings in the geometry defined by planes at 1 mm spacing; the straggling correction is essential, however, for correct execution of the calculation so specified. When the complete modification is applied, the computed results are essentially identical whether a track crosses 150 or 3 surfaces in the first 15 cm of travel.

Looking at the flux distribution on a plane is a more sensitive test of the effect of these modifications. In Figure 3, the proton flux is shown on the plane 15 cm deep into the water after 150 surface crossings. Again, due to the many surface crossings, the energy correction add little; the modification agrees very well with the LAHET tracking algorithm. A completely different picture appears in Figure 4, where the flux at 15 cm depth is obtained after only 3 surface crossing. In this case, it is the energy correction that is essential. The straggling correction adds little, since the current method applies straggling correctly when the distance of an energy step is much smaller than the thickness of a region (as defined by the explicit geometry). *Note:* in all the plots where “flux” is shown, it actually has the units  $10(\text{cm})^{-2}(\text{MeV})^{-1}$ .

Additional examples are shown in Figures 5 and 6. In the former, the flux is shown at 1 cm depth, shorter than a full energy step. The asymmetric form of the flux distribution is noticeable. In Figure 6, the flux is shown for a very thin region 1 mm thick. The shape is characteristic of the Landau distribution. The agreement between the LAHET3 results and the results from modified MCNPX appear to validate the implementation of the energy straggling models. The limitations of the numerical methods in this case are also obvious.

As a final part of this evaluation, the results shown in Figure 7 are presented. In this case, the sensitivity of the flux calculation to the number of substeps per energy step is presented. The results are somewhat disconcerting. Further review of the new coding may reveal some correctable limitation sensitive to step size. Little of the fluctuation in shape is statistical; the *estep* = 30 case was run for  $6.5 \times 10^5$  histories, the other cases for  $10^6$ . The *shift* in the flux peak is more significant. It is likely to result from the know fact that the sampling scheme is not unbiased. From numerical limitations, the mean value  $\|\Delta(E, p)\| \neq 0$ , and the bias varies considerably over the range of parameters included in this comparison. Further documentation of the numerical properties of the straggling routines is called for. There are six different algorithms covering the full range of usage. The current tests reached four of them, although the cases for *estep* = 1, 3, 6 employed the same one over most samplings.

## V. Conclusions and Recommendations

The modified algorithm presented here has been tested only on the specific problem described above. Further testing should be conducted for a variety of geometries, compositions and energies to insure proper implementation. However, the current method provides a correct application on each track length segment, including substeps, within the limitations of the models for energy loss, energy straggling and multiple scattering. It is in principal independent of geometry and is effective for thin as well as thick regions. It should be fully compatible with tallying in an overlaid mesh geometry, although that has not been tested here. As such, it should be used as the “base case” from which further approximations, simplifications and efficiencies may be applied.

For the conditions of the test case (no nuclear interactions), and using the default 3 substeps per energy step, the full modification increased the execution time by 67% for the thick-cell (5 cm) geometry and by 53% for the thin-cell (1 mm) geometry. For the straggling correction alone, the increase was 45% and 40% respectively. Applying the energy correction alone actually *reduced* execution time, 15% and 3% respectively, because the correct energy loss leads to earlier termination.

A more efficient algorithm may be constructed by applying the energy straggling with an accumulated patch length after, for instance, a full energy step (and at each surface crossing or interaction, of course), rather than each substep. Theoretically it is a valid application, but should be made an input option since it could have adverse effects on mesh tallying; all the variance in the energy straggling would be applied on the *last* substep!

Efficiency could also be improved by reducing the need for a large number of substeps per step, the motivation for which is both the desire to minimize the energy change between applications of multiple scattering and to minimize the transverse tracking error on each

path segment. It may be possible to define an “effective energy” over a path segment that will allow an accurate application of multiple scattering over larger step sizes. Furthermore, the use of a “transverse longitudinal correction (TLC)” in tracking might minimize the need for many substeps.

To conclude, here are a few minor suggestions to be considered.

- Attempting to execute the energy straggling routines in the large step (“Gaussian”) regime should result in at least a warning error; if necessary, a limiting step length may be simply applied to prevent such an occurrence.
- Allow separate substep factors for each call of particles by mass: electrons, mesons and baryon (perhaps *estep*, *mstep* and *pstep*).
- Remove the warning message for *estep* < 3, at least when electrons are not being transported, but keep the default at 3.
- Extend this comparison to examine the estimation of the angular dispersion as a function of depth in target.
- Use DBCN control of *both* multiple scattering *and* energy straggling for the foreseeable future to facilitate testing.

## REFERENCES

- [1] J. V. Siebers, Medical College of Virginia, Virginia Commonwealth University (personal communication).
- [2] H. G. Hughes, R. E. Prael, and R. C. Little, “MCNPX – The LAHET/MCNP Code Merger”, X-Division Research Note XTM-RN(U)97-012, LA-UR-97-4891, Los Alamos National Laboratory (April 1997).

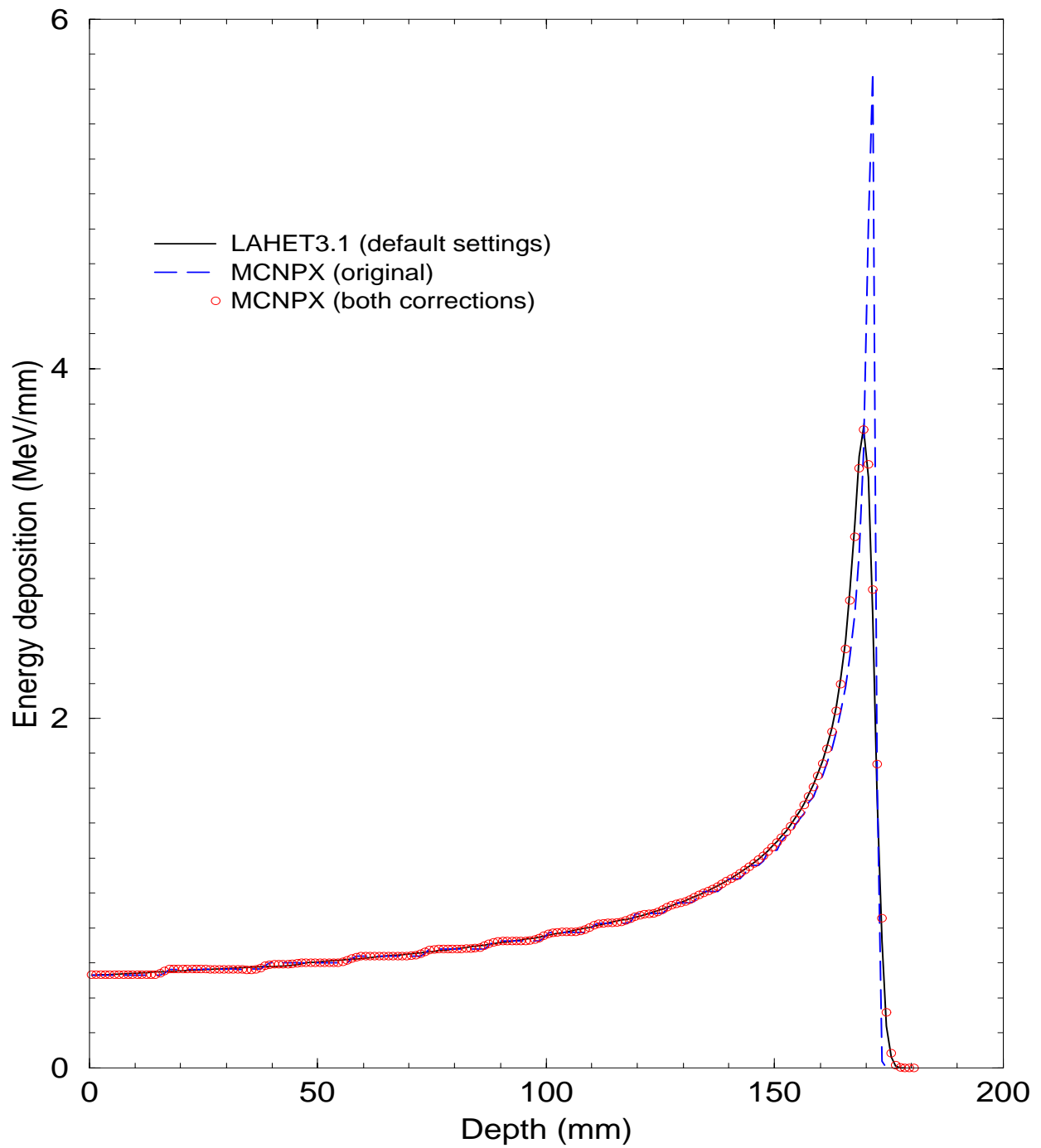


Figure 1: Energy deposition from 157.2 MeV proton beam in water, tracked through 1 mm thick regions.

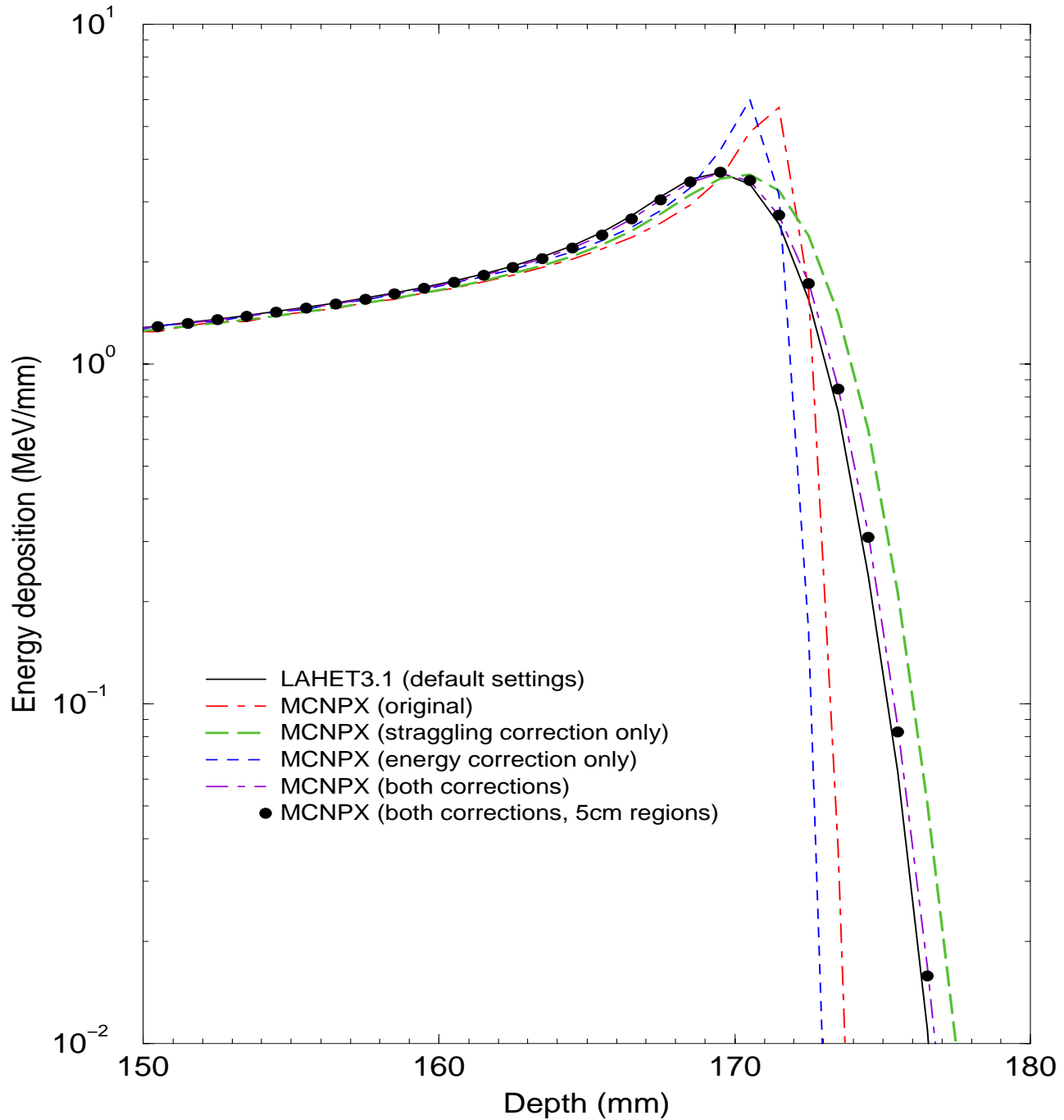


Figure 2: Energy deposition from 157.2 MeV proton beam in water, tracked through 1 mm thick regions except as indicated. The specific effect of each modification is shown.

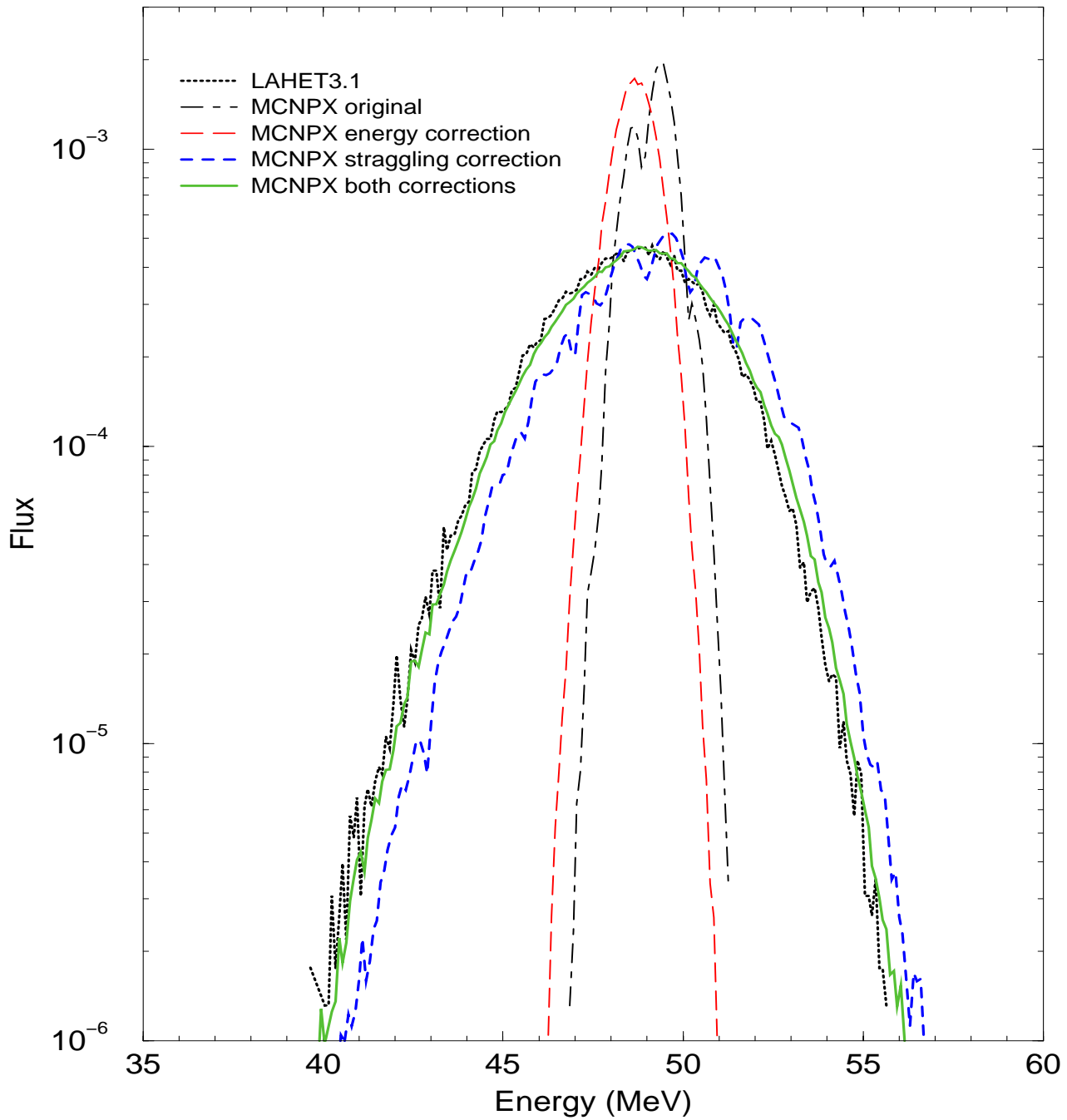


Figure 3: Flux distribution from 157.2 MeV proton beam at 15 cm depth in water, tracked through 1 mm thick regions using estep=3. The specific effect of each modification is shown.



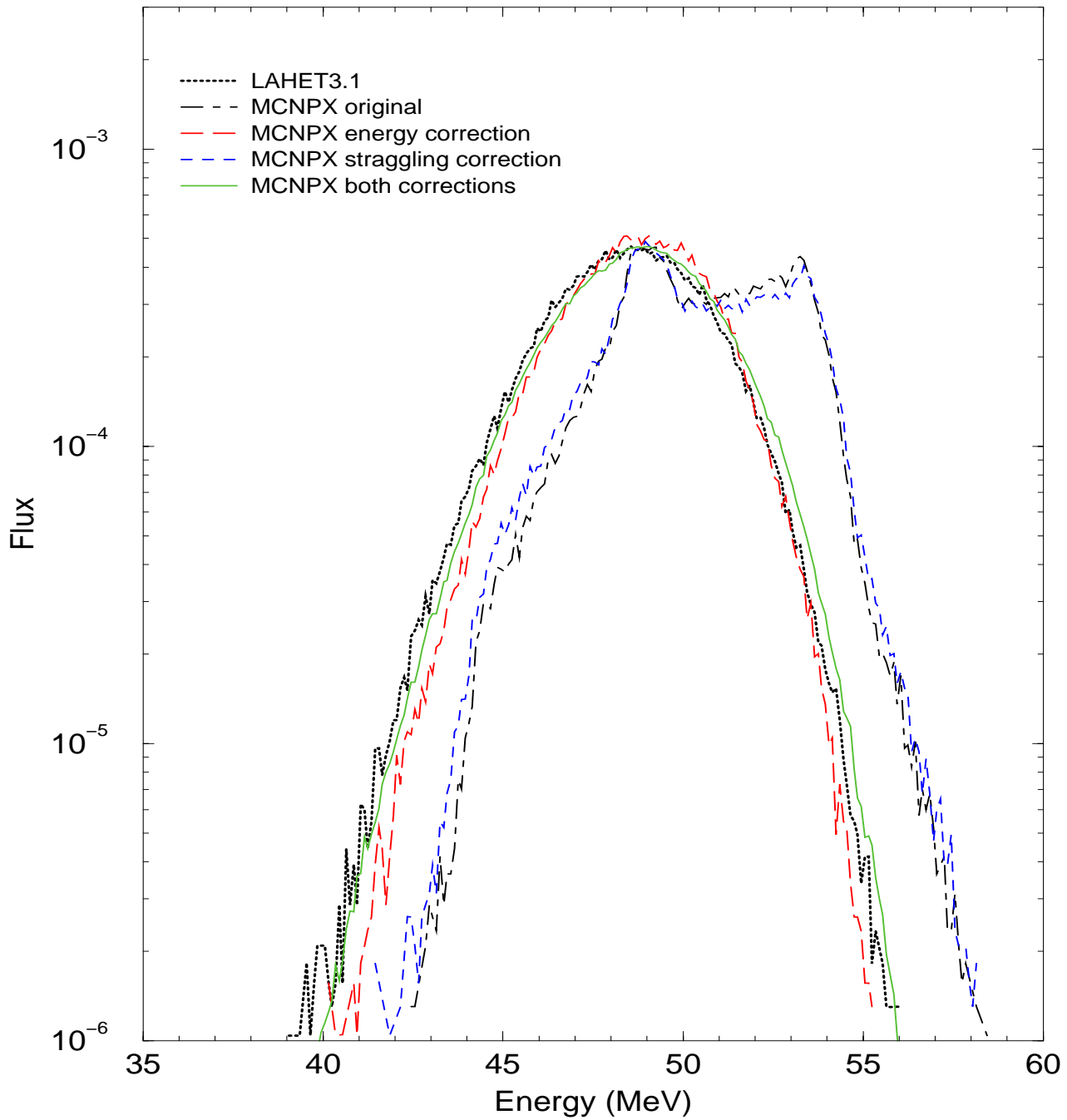


Figure 4: Flux distribution from 157.2 MeV proton beam at 15 cm depth in water, tracked through 5 cm thick regions using estep=3. The specific effect of each modification is shown.

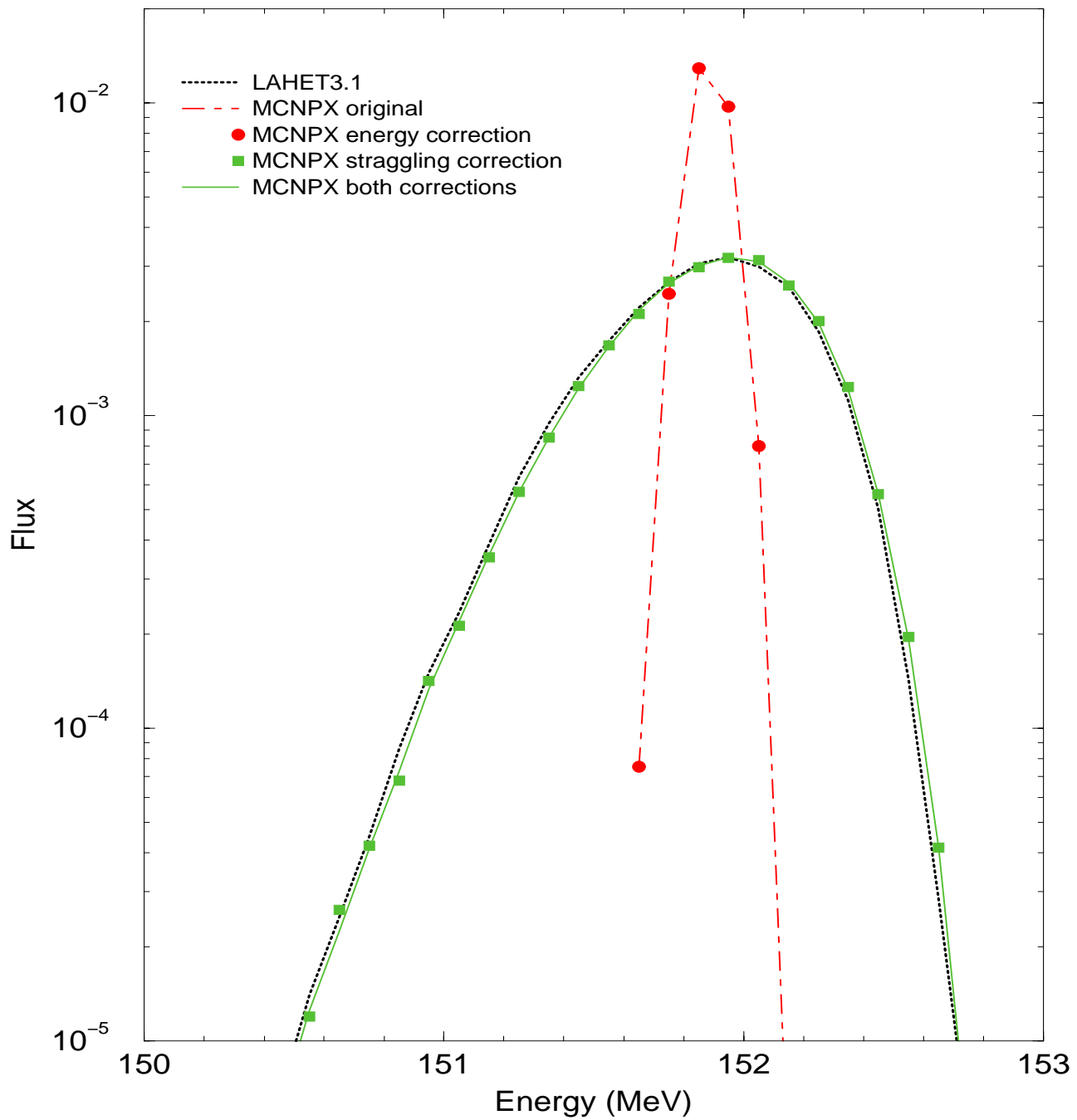


Figure 5: Flux distribution from 157.2 MeV proton beam at 1 cm depth in water, tracked through 1 mm thick regions using  $\text{estep}=3$ . The specific effect of each modification is shown.

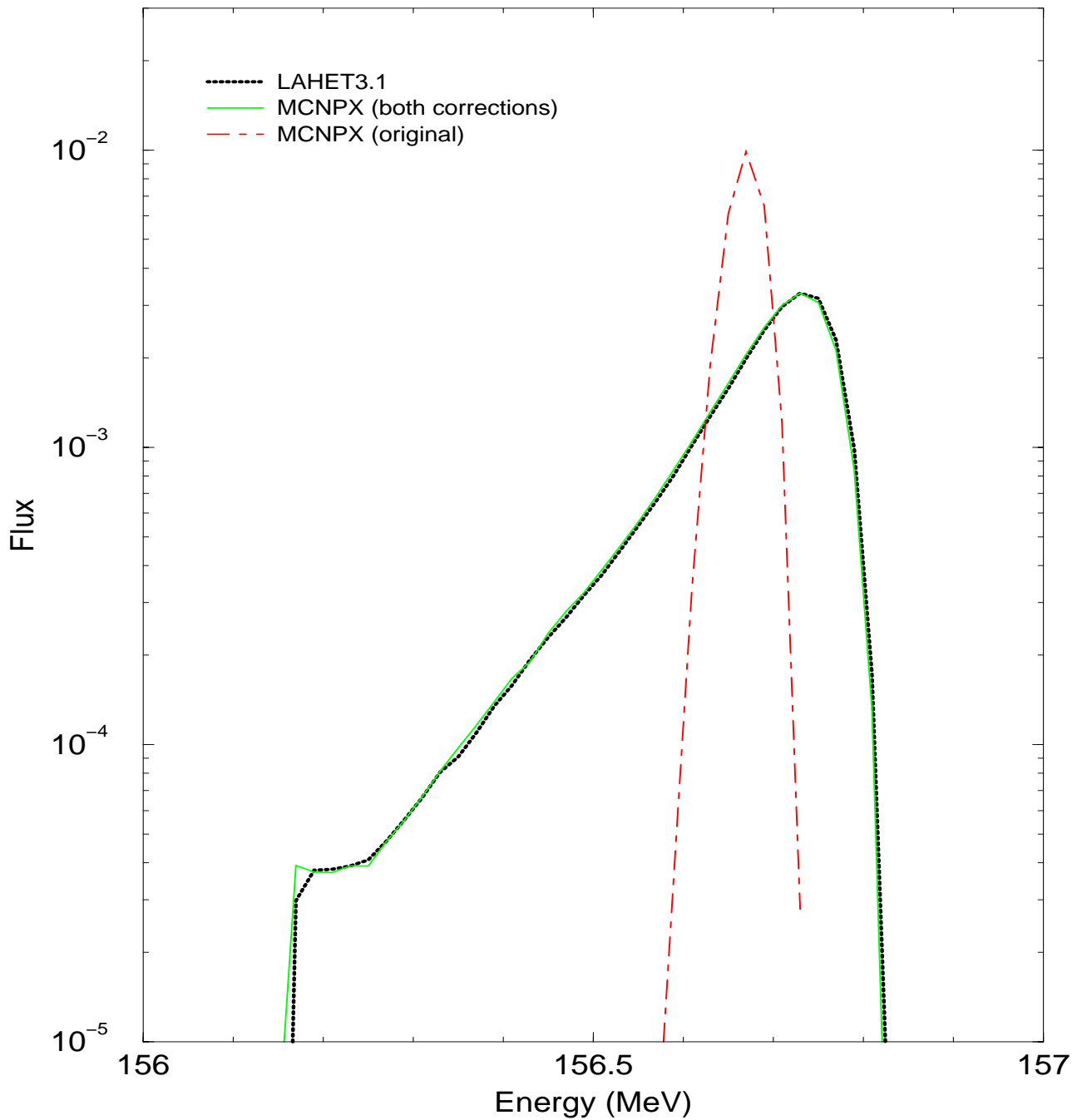


Figure 6: Flux distribution from 157.2 MeV proton beam at 1 mm depth. The specific effect of each modification is shown.

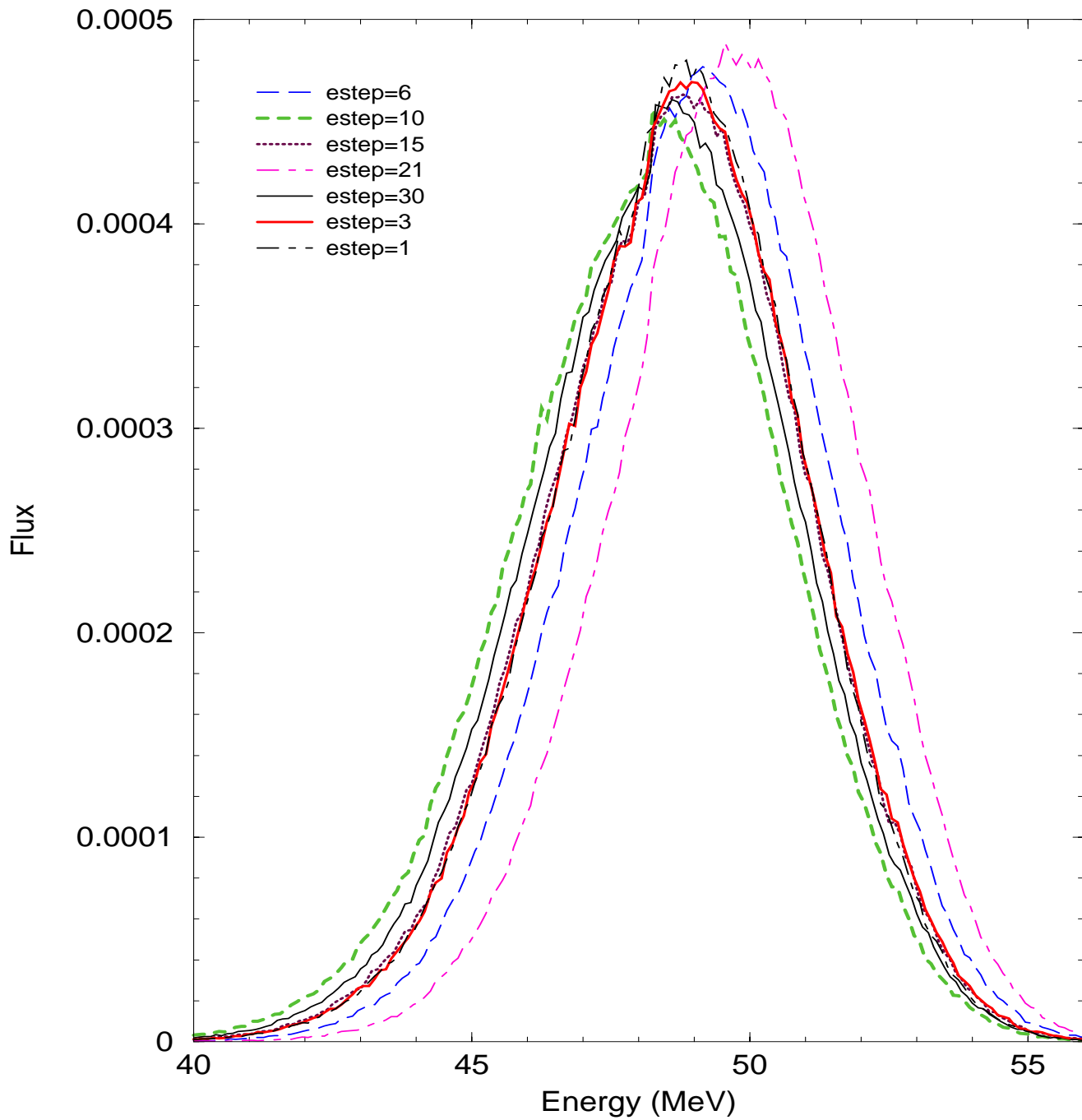


Figure 7: Effect of *ESTEP* value on flux at 15 cm depth in water, tracked through 5 cm thick regions.

**Listing of modifications to subroutine chg\_pl.F  
(enclosed by CREP comments)**

c_deck chg_pl chg_pl	chg_pl	1
subroutine chg_pl	chg_pl	2
*		
*		
*		
c	chg_pl	43
c        begin an energy step (a set of substeps).	chg_pl	44
40 pmf=huge	chg_pl	45
c        Initializing qs is probably unnecessary.		
qs=0.0		
if(mkc.ne.0) then	chg_pl	46
pmf=drs(ldrs+ipt,ngp+nee_max*(mkc-1))/rho(lrho+icl)	chg_pl	47
CREP begin #1		
qs=qav(lqav+ipt,ngp+nee_max*(mkc-1))*rho(lrho+icl)		
C        p=pmf*nsb(lnsb+mkc)	chg_pl	48
C        DEBUG: counting of resamplings of straggling.		
C        iz = 0		
C 50    call glando(rang,p,avz(lavz+mkc),ava(lava+mkc),den(lden+icl),	chg_pl	49
C 1        erg,gpt(ipt),de,ii)	chg_pl	50
C        qs=qav(lqav+ipt,ngp+nee_max*(mkc-1))*rho(lrho+icl)+de/p	chg_pl	51
C        if(qs.le.0.) then		
C            iz = iz + 1		
C            if(iz.gt.1000) then		
C                call expirx(1,'chg_pl',		
C 1                'more than 1000 resamplings of glando.')		
C                return		
C            endif		
C        go to 50		
C    endif		
CREP end #1		
endif	chg_pl	52
c	chg_pl	53
c        substep loop.	chg_pl	54
do 150 ns=nm,1,-1	chg_pl	55
if(wgt.le.0.) then	chg_pl	56
call expirx(1,'chg_pl',	chg_pl	57
1 'the weight of the current particle is zero or less.')	chg_pl	58
return	chg_pl	59
endif	chg_pl	60
nch(ipt)=nch(ipt)+1	chg_pl	61
ncp=ncp+1	chg_pl	62
n1=ngp	chg_pl	63
#ifdef MESHTAL		
f_ed=0.0		
#endif		
c	chg_pl	64
c        calculate distances to time and energy cutoff.	chg_pl	65
dte=vel*(tco(ipt)-tme)	chg_pl	66
dc=huge	chg_pl	67
if(mkc.ne.0)dc=(erg-elc(ipt))/qs	chg_pl	68
c	chg_pl	69
c        calculate the distance to interaction.	chg_pl	70

```

        di=huge                                chg_pl      71
        if(ipt.eq.9.and.jan.eq.1) then          chg_pl      72
            call ace_tot(erg,lp,mkc,nel(lnel+1),mel(lmel+1),aa9(laa9+1),
1          sigg(lsgg+1,1),hsigg(lhsg+1,1),xsiso(lxso+1,1),esxmp(lesp+1),
2          esxln(lexn+1,1),rho(lrho+ic1),di)      chg_pl      75
        else                                    chg_pl      76
            call get_tot(erg,lp,mkc,nel(lnel+1),mel(lmel+1),aa9(laa9+1),
1          sigg(lsgg+1,1),hsigg(lhsg+1,1),xsiso(lxso+1,1),rho(lrho+ic1),
2          di)                                    chg_pl      79
        endif                                    chg_pl      80
c                                                chg_pl      81
c        calculate the distance to the cell boundary, dls.    chg_pl      82
        d1=min(pmf,dtc,di,dc)                   chg_pl      83
        if(mbd(lmbd+ic1).ne.0.or.jsu.ne.0)go to 60    chg_pl      84
        dls=huge                                 chg_pl      85
        rr=rr-d1                                 chg_pl      86
        if(rr.gt.0.)go to 70                      chg_pl      87
        rr=dbmin()-d1                             chg_pl      88
        if(rr.gt.0.)go to 70                      chg_pl      89
60 if(lca(1lca+ic1).lt.0)call chkcel(ic1,3,j)      chg_pl      90
        call track(ic1)                           chg_pl      91
        if(kdb.ne.0)return                        chg_pl      92
        jsu=jap                                    chg_pl      93
70 continue                                       chg_pl      94
c                                                chg_pl      95
c        tally the track length in the cell.            chg_pl      96
        d=min(dls,d1)                             chg_pl      97
            *
            *
            *
c        scatter the particle.                    chg_pl     114
        uold(1)=uuu                                chg_pl     115
        uold(2)=vvv                                chg_pl     116
        uold(3)=www                                chg_pl     117
        if(mkc.ne.0) then                          chg_pl     118
c                                                chg_pl     119
c        TEMPORARY measure: default gaussian; dbcn(21) for no scatter.
        if(dbcn(21).eq.0.) then
            call mscat3(lp,d,arg(larg+mkc),erg,th)
            call rotas(cos(th),uold,uuu,lev,irt)
        endif
c                                                chg_pl     121
c        lose energy to ionization along the track.      chg_pl     122
        eg0=erg                                    chg_pl     123
CREP begin #2
        d_left=d
        n2=ngp
        qs1=qs
45 continue
        dps=(erg-eee(1eee+ipt,n2+1))/qs1
        if (d_left.le.dps) then
            erg=erg-qs1*d_left
        else
            d_left=d_left-dps
            n2=n2+1

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```

        erg=eee(lee+ipt,n2)
C      qs1=qs1*qav(lqav+ipt,n2+nee_max*(mkc-1))/
C      1      qav(lqav+ipt,n2-1+nee_max*(mkc-1))
        qs1=qav(lqav+ipt,n2+nee_max*(mkc-1))*rho(lrho+ic1)
        go to 45
      endif
c      DEBUG: counting of resamplings of straggling.
      iz = 0
50     call glando(rang,d,avz(lavz+mkc),ava(lava+mkc),den(lden+ic1),
      1      eg0,gpt(ipt),de,ii)
      if((eg0-erg+de).le.0.) then
        iz = iz + 1
        if(iz.gt.1000) then
          call expirx(1,'chg_pl',
      1      'more than 1000 resamplings of glando.')
          return
        endif
        go to 50
      endif
      erg=erg-de
      paxtc(6,11,ipt)=paxtc(6,11,ipt)+wgt*(eg0-erg)
#ifdef MESHTAL
      f_ed=eg0-erg
CREP end #2
      l=locct(11ct+1,ic1)
      if(l.ne.0)call tally(f_ed,1,1,d)
      if(kdb.ne.0)return
      do 76 i=0,lev-1
        l=locct(11ct+1,int(udt(7,i)))
      76      if(l.ne.0)call tally(f_ed,1,1,d)
      if (mtlflg.ne.0.or.medflg.ne.0.and.f_ed.ne.0.) then
        do 78 i=1,6
          if(lev.eq.0) then
            zd(i)=gpblcm(i)
          else
            zd(i)=udt(i,0)
          endif
        78      continue
        zd(7)=wgt
        zd(8)=erg
        zd(9)=f_ed
        jz(1)=mkc
        jz(5)=2
        call gdtal(2,d,zd,jz)
      endif
#endif
#ifdef CREP begin #3
      if(erg.le.elc(ipt)) then
CREP end #3
        call uplpos(xxx,uold,lev,d,vel,1)
c      to avoid a roundoff problem...
        erg=elc(ipt)
        nb=2
        go to 500
      endif

```

	chg_pl	127
	chg_pl	128
	chg_pl	129
	chg_pl	130
	chg_pl	131
	chg_pl	132

c		chg_pl	133
	if(erg.lt.eee(lee+ipt,ngp+1)) then	chg_pl	134
100	ngp=ngp+1	chg_pl	135
	if(erg.lt.eee(lee+ipt,ngp+1))go to 100	chg_pl	136
	endif	chg_pl	137
	endif	chg_pl	138
c		chg_pl	139
c	move particle to surface, substep, interaction, or termination.	chg_pl	140
c	produce secondary particles.	chg_pl	141
	*		
	*		
	*		
c	complete energy substep for particle remaining in cell icl.	chg_pl	218
150	if(nl.ne.ngp)go to 40	chg_pl	219
	go to 40	chg_pl	220
c		chg_pl	221
500	ec=erg	chg_pl	222
	*		
	*		
	*		
	return	chg_pl	241
	end	chg_pl	242